Error Analysis of Common Sampling Stratgies

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Gurprit Singh

gsingh@mpi-inf.mpg.de











Jitter





Jitter

Poisson Disk











Variance Convergence Rate of Samplers



Number of Samples



Number of Samples

Variance Convergence Rate of Samplers Random 4D Jittered Poisson Disk



Fredo Durand [2011] Subr & Kautz [2013] Pilleboue et al. [2015]

Number of Samples

Stratification strategies



Blue noise sampling and beyond

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Importance sampling

with correlated samples



Regular grid samples





Regular grid

Pauly et al. [2000]

Regular



Uniformly jittered regular grid





Uniform jitter

Pauly et al. [2000]

Regular







Random jitter

Pauly et al. [2000]

Regular

Uniform jitter







Random jitter

Pauly et al. [2000]

Regular

Uniform jitter

Random jitter









Pauly et al. [2000]

Regular

Uniform jitter

Random jitter







Uniform jitter



Uniform jitter (RMS 13.4%)



Random jitter (RMS 10.4%)



Ramamoorthi et al. [2012]









Random jitter





Canoncial square domain

Occluded

Visible



Uniform jitter (RMS 6.59%)

Random jitter (RMS 8,32%)



Uniform jitter



Uniform jitter (RMS 13.4%)

Random jitter (RMS 10.4%)



19





[2012]

Polar mapping performs better for some samplers compared to concentric mapping

observed by Andrew Kensler [2013]







Canoncial square domain



Visible

Per Christensen [2018]









Disk area light source



Polar mapping

Per Christensen [2018]







Occluded

Visible



Disk area light source



Concentric mapping Shirley and Chiu [1997]

Polar mapping

Per Christensen [2018]





Disk area light source

Reference





Cengiz Oztireli [2016]



Disk area light source

Reference



Random jitter



RMS 11.21%



RMS 10.92%

Uniform jitter



RMS 10.79%

RMS 11.77%

Cengiz Oztireli [2016]



Disk area light source

Reference



Random jitter



RMS 11.21%



RMS 10.92%

Uniform jitter

Isotropic jitter





RMS 10.79%

RMS 8.00%

RMS 11.77%

RMS 8,77%

engiz Oztireli [2016]

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Isotropic jitter = uniform jitter + random rotation



Rotated uniform jitter better for not too complex shadows









Blue noise sampling and beyond

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Fourier analysis of sample correlations

Expected power spectrum for random samples



Expected power spectrum for jittered samples







Samples



Variance in terms of power spectra





Fredo Durand [2011] Pillebuoe et al. [2015]



Variance in terms of power spectra

Samples' expected power spectrum



 $\operatorname{Var}(I_N) \propto$



 \times

Integrand power spectrum





Fredo Durand [2011] Pillebuoe et al. [2015]



Variance in terms of power spectra

Samples' expected power spectrum



 $\operatorname{Var}(I_N) \propto$

Integrand power spectrum



Fredo Durand [2011] Pillebuoe et al. [2015]


Variance in terms of power spectra

Samples' expected power spectrum



 $\operatorname{Var}(I_N) \propto$

Integrand power spectrum



Fredo Durand [2011] Pillebuoe et al. [2015]



Variance in terms of power spectra

Samples' expected Integrand power spectrum power spectrum





Pillebuoe et al. [2015]

Variance in terms of power spectra

Samples' expectedIntegrandpower spectrumpower spectrum







Convergence rate depends on the low frequency region

Samples' expected Integrand power spectrum power spectrum



Samplers	Wors
Random	$\mathcal{O}($
Poisson Disk	$\mathcal{O}($
Jitter	$\mathcal{O}($
CCVT	$\mathcal{O}($





Jittered samples converges faster than Poisson Disk



Convergence rate depends on the low frequency region

Samples' expected Integrand power spectrum power spectrum



Samplers	Wor
Random	$\mathcal{O}($
Poisson Disk	$\mathcal{O}($
Jitter	$\mathcal{O}($
CCVT	$\mathcal{O}($



Isotropic Spectrum Poisson Disk













Initialize





Shuffle rows







Shuffle columns

















N-rooks / Latin Hypercube

N-rooks Spectrum







N-rooks / Latin Hypercube

Spectrum





N-rooks / Latin Hypercube

N-rooks Spectrum





N-rooks / Latin Hypercube

N-rooks Spectrum





Jitter

Jitter Spectrum



N-rooks / Latin Hypercube

N-rooks Spectrum





Multi-Jitter

Multi-Jitter Spectrum

Chiu et al. [1993]





N-rooks / Latin Hypercube

N-rooks Spectrum



Multi-jitter

Multi-Jitter Spectrum

Chiu et al. [1993]





N-rooks / Latin Hypercube

N-rooks Spectrum



Multi-jitter

Multi-Jitter Spectrum

Chiu et al. [1993]

Sampling in Higher Dimensions



4D Sampling 2D 2D (u_1, v_1) (x_1, y_1) (u_2, v_2) (x_2, y_2) (u_3, v_3) (x_3, y_3) (u_4, v_4) (x_4, y_4) 4D (x_1, y_1, u_3, v_3) (x_2, y_2, u_1, v_1) (x_3, y_3, u_4, v_4) (x_4, y_4, u_2, v_2) 58



4D Sampling 2D 2D (u_1, v_1) (x_1, y_1) (u_2, v_2) (x_2, y_2) (u_3, v_3) (x_3, y_3) (u_4, v_4) (x_4, y_4) 4D (x_1, y_1, u_3, v_3) (x_2, y_2, u_1, v_1) (x_3, y_3, u_4, v_4) (x_4, y_4, u_2, v_2)



4D Sampling 2D 2D (u_1, v_1) (x_1, y_1) (u_2, v_2) $[x_2, y_2]$ (u_3, v_3) (x_3, y_3) (u_4, v_4) (x_4, y_4) 4D (x_1, y_1, u_3, v_3) (x_2, y_2, u_1, v_1) (x_3, y_3, u_4, v_4) (x_4, y_4, u_2, v_2) 60

4D Sampling Spectra along Projections





4D Sampling Spectra along Projections



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4D Sampling Spectra along Projections



Power Spectrum





Power

Power



Power Spectrum





Power

Power





N-rooks spectrum













Pixel B

Non-Axis Aligned Integrand Spectra

 $\mathcal{P}_f(
u)$



Integrand Spectrum



Non-Axis Aligned Integrand Spectra



Multi-jittered Samples

 $\left\langle \mathcal{P}_{S_N}(\nu) \right\rangle$

 $\mathcal{P}_f(\nu)$





Sampling Spectrum

Integrand Spectrum



Shearing Multi-Jittered Samples



Sheared Samples

 $\left\langle \mathcal{P}_{S_N}(\nu) \right\rangle$





Sheared Spectrum

Integrand Spectrum

Singh and Jarosz [SIGGRAPH 2017]





Variance HeatmapWith Original SamplesMultiple images



Uncorrelated Multi-jittered


Variance Heatmap With Original Samples With Sheared Samples



Uncorrelated Multi-jittered



Blue noise samplers can have better convergence compared to stratified samples

Denser stratification can lead to anisotropic spectra which improves convergence

So far...

What properties we desire in a sampler?



Progressivity (Ahmed et al. [2017], Christensen et al. [2018])

High speed (millions of samples per second)

Extension to dimensions beyond 2D (Spoke dart throwing, Mitchell [2018])



non-progressive progressive





Low-Discrepancy Sampling

distributed (have low discrepancy).

Entire field of study called Quasi-Monte Carlo (QMC)

Deterministic sets of points specially crafted to be evenly

The Van der Corput Sequence

Radical Inverse Φ_b in base 2 Subsequent points "fall into biggest holes"

k	Base 2	Φ_b
1	1	.1 = 1/2
2	10	.01 = 1/4
3	11	.11 = 3/4
4	100	.001 = 1/8
5	101	.101 = 5/8
6	110	.011 = 3/8
7	111	.111 = 7/8

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Halton and Hammersley Points

- Halton: Radical inverse with different base for each dimension:
 - $\vec{x}_k = (\Phi_2(k), \Phi_3(k), \Phi_5(k), \dots, \Phi_{p_n}(k))$
- The bases should all be relatively prime.
- Incremental/progressive generation of samples
- **Hammersley**: Same as Halton, but first dimension is k/N:
- $\vec{x}_k = (k/N, \Phi_2(k), \Phi_3(k), \Phi_5(k), \dots, \Phi_{p_n}(k))$ - Not incremental, need to know sample count, *N*, in advance



Why do we need to scramble?

Halton Projection (29, 31)

Scrambled Halton Projection (29, 31)

Scrambled Low-Discrepancy Sampling

Monte Carlo (16 jittered samples)

Can we combine blue noise properties with low discrepancy?

Low-Discrepancy Blue Noise

DBN Step

step spectru

-DBN BNOT

BNOT spectrum

90

Low-Discrepancy Blue Noise

Ahmed et al. [2016]

Low-Discrepancy Blue Noise

Log Number of samples

Ahmed et al. [2016]

Low-Discrepancy Blue Noise 2D-Projections

Sobol

Perrier et al. [2018]

Low-Discrepancy Blue Noise 2D-Projections

Sobol

Special scrambling

Perrier et al. [2018]

Low-Discrepancy Blue Noise 2D-Projections

Sobol

Special scrambling

Blue noise characteristics

Perrier et al. [2018]

Low-Discrepancy Blue Noise 2D Sobol Projections

Sobol sequence

Perrier et al. [2018]

Fourier

Blue noise sampling and beyond • • • • • • • ...

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Importance sampling

with correlated samples

Light Importance Sampling

Light IS vs BSDF IS

BSDF Importance Sampling

Singh et al. [2019]

Scene illuminated by area direct lighting

Underlying pixel functions

Singh et al. [2019]

Unoccluded pixels' convergence benefit from Light IS

Underlying pixel functions

Pixel P

Singh et al. [2019]

100

Occluded pixels (no improvement in convergence)

Singh et al. [2019]

Futuristic sampling target spectrum

Multi-jittered

Future design

Singh and Jarosz [2017]

Future research directions

Progressive samplers in higher dimensions

Adapting sample correlations w.r.t. the underlying integrand in high dimensions

Direct link between spatial and Fourier statistics needs further investigation

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