

Eurographics 2015

The 36th Annual Conference of the European Association for Computer Graphics

Recent Advances in Adaptive Sampling and Reconstruction for Monte Carlo Rendering Derivative Analysis

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Path tracing - diffuse scene



128 paths/pixel



Thursday, July 16, 15

Diffuse indirect illumination is smooth





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Diffuse indirect illumination is smooth



Perfect candidate for sparse sampling and interpolation



Interpolated indirect illumination



Irradiance Caching [Ward et al. 1988]

1M pixels - 4K cache points



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[Ward et al. 1988] 5

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else

Compute and cache a new illumination value at **x**.



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Compute and cache a new illumination value at **x**.

- Some questions that remain:
 - What do we cache?
 - What makes a cache point "nearby"?
 - How do we interpolate the nearby cached values?



$$L_r(\mathbf{x}, \vec{\omega}_r) = \int_{H^2} f_r(\mathbf{x}, \vec{\omega}_i, \vec{\omega}_r) L_i(\mathbf{x}, \vec{\omega}_i) (\vec{\mathbf{n}} \cdot \vec{\omega}_i) \, \mathrm{d}\vec{\omega}_i$$



$$L_r(\mathbf{x}, \vec{\omega}_r) = \int_{H^2} f_r(\mathbf{x}, \vec{\omega}_i, \vec{\omega}_r) L_i(\mathbf{x}, \vec{\omega}_i) (\vec{\mathbf{n}} \cdot \vec{\omega}_i) \, \mathrm{d}\vec{\omega}_i$$



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$$= \frac{\rho}{\pi} \int_{H^2} L_i(\mathbf{x}, \vec{\omega}_i) (\vec{\mathbf{n}} \cdot \vec{\omega}_i) \, \mathrm{d}\vec{\omega}_i$$



$$L_{r}(\mathbf{x}, \vec{\omega}_{r}) = \int_{H^{2}} f_{r}(\mathbf{x}, \vec{\omega}_{i}, \vec{\omega}_{r}) L_{i}(\mathbf{x}, \vec{\omega}_{i}) (\vec{\mathbf{n}} \cdot \vec{\omega}_{i}) \, \mathrm{d}\vec{\omega}_{i}$$
$$= \frac{\rho}{\pi} \underbrace{\int_{H^{2}} L_{i}(\mathbf{x}, \vec{\omega}_{i}) (\vec{\mathbf{n}} \cdot \vec{\omega}_{i}) \, \mathrm{d}\vec{\omega}_{i}}_{E(\mathbf{x}, \vec{\mathbf{n}}) \rightarrow \mathrm{Irradiance}}$$



$$L_{r}(\mathbf{x}, \vec{\omega}_{r}) = \int_{H^{2}} f_{r}(\mathbf{x}, \vec{\omega}_{i}, \vec{\omega}_{r}) L_{i}(\mathbf{x}, \vec{\omega}_{i}) (\vec{\mathbf{n}} \cdot \vec{\omega}_{i}) \, \mathrm{d}\vec{\omega}_{i}$$
$$= \frac{\rho}{\pi} \underbrace{\int_{H^{2}} L_{i}(\mathbf{x}, \vec{\omega}_{i}) (\vec{\mathbf{n}} \cdot \vec{\omega}_{i}) \, \mathrm{d}\vec{\omega}_{i}}_{E(\mathbf{x}, \vec{\mathbf{n}}) \longrightarrow \text{Irradiance}}$$
$$E(\mathbf{x}, \vec{\mathbf{n}}) \approx \frac{\pi}{N} \sum_{j=1}^{N} L_{i}(\mathbf{x}, \vec{\omega}_{i,j})$$



- Irradiance computation costly, reuse whenever possible
- How far away can we reuse a cached value?





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• To compute valid region, need to estimate change in irradiance $\partial E_{\Delta = -1} \partial E_{\Delta = -1}$

$$\frac{\partial E}{\partial \mathbf{x}} \Delta \mathbf{x} + \frac{\partial E}{\partial \vec{\mathbf{n}}} \Delta \vec{\mathbf{n}}$$

- Consider hypothetical,
 - worst-case scene:
 - the "Split-Sphere"

• To compute valid region, need to estimate change in irradiance $\left|\frac{\partial E}{\partial \mathbf{x}} + \frac{\partial E}{\partial \mathbf{x}}\right|$

$$\varepsilon_i \lesssim \left| \frac{\partial L}{\partial \mathbf{x}} \Delta \mathbf{x} + \frac{\partial L}{\partial \vec{\mathbf{n}}} \Delta \vec{\mathbf{n}} \right|$$

• Consider hypothetical,

worst-case scene:

the "Split-Sphere"

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[Ward et al. 1988] 9

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• To compute valid region, need to estimate change in irradiance ∂E , ∂E ,

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[Ward et al. 1988] 10

$$\varepsilon_i \lesssim \left| \frac{\partial E}{\partial \mathbf{x}} \Delta \mathbf{x} + \frac{\partial E}{\partial \vec{\mathbf{n}}} \Delta \vec{\mathbf{n}} \right|$$

$$\varepsilon_i \lesssim E_i \left(\frac{4}{\pi} \frac{\|\mathbf{x} - \mathbf{x}_i\|}{R_i} + \sqrt{1 - (\vec{\mathbf{n}} \cdot \vec{\mathbf{n}}_i)} \right)$$

• At each shading location, perform a weighted average of all cached values which have an error below some threshold.

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$$E(\mathbf{x}, \vec{\mathbf{n}}) \approx \frac{\sum_{i \in S} w_i(\mathbf{x}, \vec{\mathbf{n}}) E_i}{\sum_{i \in S} w_i(\mathbf{x}, \vec{\mathbf{n}})}$$

here:
$$S = \{i : \epsilon_i(\mathbf{x}, \vec{\mathbf{n}}) < a\}$$

W

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here:
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[Ward et al. 1988] 15

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W
Interpolating Irradiance

- At each shading location, perform a weighted average of all cached values which have an error below some threshold.
- Reciprocal of the error is used as the weight





Irradiance Caching

- Pros:
 - Independent of resolution.
 - Computation amortized across many pixels
 - Concentrates computation in visible regions were illumination changes rapidly

[Ward et al. 1988]

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Irradiance Caching

- Cons:
 - Interpolation/extrapolation can introduce visible artifacts
 - Valid radius metric not always robust
 - Limited to Lambertian (matte) surfaces





Improvements/Extensions

- Many extensions:
 - Ward and Heckbert '92 better interpolation
 - Křivánek et al. '05a, '05b glossy surfaces
 - Jarosz et al. '08 participating media
 - Jarosz et al. '12 irradiance Hessians
 - Schwarzhaupt et al. '12 better error control



Irradiance gradients

- Improve interpolation/extrapolation quality using gradients
- Irradiance Gradients [Ward and Heckbert 1992]
 - Estimate an actual derivative to the irradiance
 - Apply this derivative to the weighted average























- Accounts for change in geometric relationship between x & y
- Ignores occlusion changes





Gradients (stratified formulation)





[Ward and Heckbert 1992] 25

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Gradients (stratified formulation)

• Considers occlusion changes





[Ward and Heckbert 1992] 26

Gradients (stratified formulation)





[Ward and Heckbert 1992] 26

Stratified irradiance gradient



Stratified irradiance gradient



$$E(\mathbf{x}, \vec{\mathbf{n}}) \approx \frac{\sum_{i \in S} w_i(\mathbf{x}, \vec{\mathbf{n}}) E_i}{\sum_{i \in S} w_i(\mathbf{x}, \vec{\mathbf{n}})}$$



$$E(\mathbf{x}, \vec{\mathbf{n}}) \approx \frac{\sum_{i \in S} \mathbf{w}_i(\mathbf{x}, \vec{\mathbf{n}}) \left(E_i + (\vec{n}_i \times \vec{\mathbf{n}}) \cdot (\vec{\nabla}_r E_i) + (\mathbf{x} - \mathbf{x}_i) \cdot (\vec{\nabla}_t E_i) \right)}{\sum_{i \in S} \mathbf{w}_i(\mathbf{x}, \vec{\mathbf{n}})}$$





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Find overlapping cache records





$$E(\mathbf{x}, \vec{\mathbf{n}}) \approx \frac{\sum_{i \in S} \mathbf{w}_i(\mathbf{x}, \vec{\mathbf{n}}) \left(E_i + (\vec{n}_i \times \vec{\mathbf{n}}) \cdot (\vec{\nabla}_r E_i) + (\mathbf{x} - \mathbf{x}_i) \cdot (\vec{\nabla}_t E_i) \right)}{\sum_{i \in S} \mathbf{w}_i(\mathbf{x}, \vec{\mathbf{n}})}$$

Extrapolate along gradients







$$E(\mathbf{x}, \vec{\mathbf{n}}) \approx \frac{\sum_{i \in S} w_i(\mathbf{x}, \vec{\mathbf{n}}) \left(E_i + (\vec{n}_i \times \vec{\mathbf{n}}) \cdot (\vec{\nabla}_r E_i) + (\mathbf{x} - \mathbf{x}_i) \cdot (\vec{\nabla}_t E_i) \right)}{\sum_{i \in S} w_i(\mathbf{x}, \vec{\mathbf{n}})}$$

Sum extrapolated values





Irradiance Gradients



• Generalization to glossy surfaces



- Generalization to glossy surfaces
- Radiance Caching [Křivánek et al. 2005a,2005b]



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- Radiance Caching [Křivánek et al. 2005a,2005b]
 - Can no longer cache just the irradiance value



- Generalization to glossy surfaces
- Radiance Caching [Křivánek et al. 2005a,2005b]
 - Can no longer cache just the irradiance value
 - Cache full hemispherical *radiance* field at sparse locations



Radiance Storage

- Use spherical or hemispherical harmonics
- Approximates smooth functions with a few coefficients



Monte Carlo





[Křivánek et al. 2005a,2005b] 37

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Radiance Caching





[Křivánek et al. 2005a,2005b] 38

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Radiance Gradients

 Improve interpolation quality by storing gradient of incoming radiance field






[Krivanek et al. 2005a]

[Krivanek et al. 2005b]

occlusion-aware



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[Křivánek et al. 2005a,2005b] 40

Beyond surfaces

- Generalizations to participating media
- Volumetric Radiance Caching [Jarosz et al. 2008a, 2008b]
 - Cache radiance and gradients within volume



[Jarosz et al. 2008a, 2008b] 41

Valid Radius





[Jarosz et al. 2008a, 2008b] ⁴²

Gradients



no gradients



[Jarosz et al. 2008a] 43

Gradients



with gradients



[Jarosz et al. 2008a] 44

Results





[Jarosz et al. 2008a] 45

Results





[Jarosz et al. 2008a] 46

Participating media



no media



with media



[Jarosz et al. 2008b] 47

Surfaces in participating media





no media (indirect irradiance)

with media (indirect irradiance)



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Surfaces in participating media



Occlusion aware, but media unaware gradients [Ward and Heckbert 92]



[Jarosz et al. 2008b] 49

Surfaces in participating media



Occlusion and media aware gradients [Jarosz et al. 2008b]



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Sun beam through window



Gradients by [Ward and Heckbert 92]



[Jarosz et al. 2008b] 50

Sun beam through window



Gradients by [Jarosz et al. 2008b]



[Jarosz et al. 2008b] 50

Higher-order derivatives

- Exploit higher-order derivatives for better error control
 - [Jarosz et al. 2012] Hessians (occlusion-unaware)
 - [Schwarzhaupt et al. 2012] occlusion-aware Hessians & practical details



Split-Sphere Heuristic

- Basis for most irradiance caching algorithms for 20+ years
- Fix-ups to original metric lead to many parameters
 - error threshold
 - min/max screen-space radii
 - min/max world-space radii
 - gradient clamping

- ...

• Hard to control!



total error ε^t = integrated difference between
extrapolated and correct irradiance





total error ε^t = integrated difference between
extrapolated and correct irradiance



$$\epsilon^t = \int_{-R_i}^{R_i} |E(\mathbf{x}_i + x) - E'(\mathbf{x}_i + x)| \, dx$$



• E' is 1st-order Taylor extrapolation



$$\epsilon^t = \int_{-R_i}^{R_i} |\mathbf{E}(\mathbf{x}_i + x) - \mathbf{E}'(\mathbf{x}_i + x)| \, dx$$



- E' is 1st-order Taylor extrapolation
- *E* is unknown!



$$\epsilon^t = \int_{-R_i}^{R_i} |E(\mathbf{x}_i + x) - E'(\mathbf{x}_i + x)| \, dx$$



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- *E* is unknown!



2nd-order Taylor extrapolation



$$\epsilon^t = \int_{-R_i}^{R_i} |E(\mathbf{x}_i + x) - E'(\mathbf{x}_i + x)| dx$$



Hessian-based Error Control

- E' is 1st-order Taylor extrapolation
- 2nd-order Taylor extrapolation approximates *E*



$$\epsilon^{t} = \int_{-R_{i}}^{R_{i}} |E(\mathbf{x}_{i} + x) - E'(\mathbf{x}_{i} + x)| dx \quad \approx \quad \hat{\epsilon}^{t} = \frac{1}{2} \int_{-R_{i}}^{R_{i}} |x \mathbf{H}_{\mathbf{x}}(E_{i}) x| dx$$



[Jarosz et al. 2012] 57

Beyond the Split-Sphere

~1,700 Cache Points





Split-Sphere

Hessian-based



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[Schwarzhaupt et al. 2012] 58

Split-Sphere vs Hessian-based



Anisotropic Cache Records







Bounded Split-Sphere

Occlusion Hessian

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Summary

- Derivatives can estimate local function smoothness
- Amortize illumination computation across many pixels
- Accounting for occlusions is challenging but critical
- Specialized techniques for diffuse or moderately glossy

