

CONCURRENT POOLS

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What is a pool?

A pool is a data structure representing a collection of objects, tasks, resources, etc.

We can add items to the pool, and remove an unspecified item from the pool.

What is it used for? When it doesn't matter which item is removed from the pool, e.g., processing a set of tasks in any order, possibly Creating new tasks simultaneously.

A concurrent pool supports simultaneous access by many processes.

CONCURRENT POOL

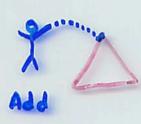
Goals:

- · avoid interference between procs
- · maintain locality of reference
- · efficient access for all processes

Partition the pool into local segments, one per process:







Our Study

Compares 3 implementations of concurrent pools.

The steal operation becomes the dominant factor in performance :

- · interference with others
- · non-local references

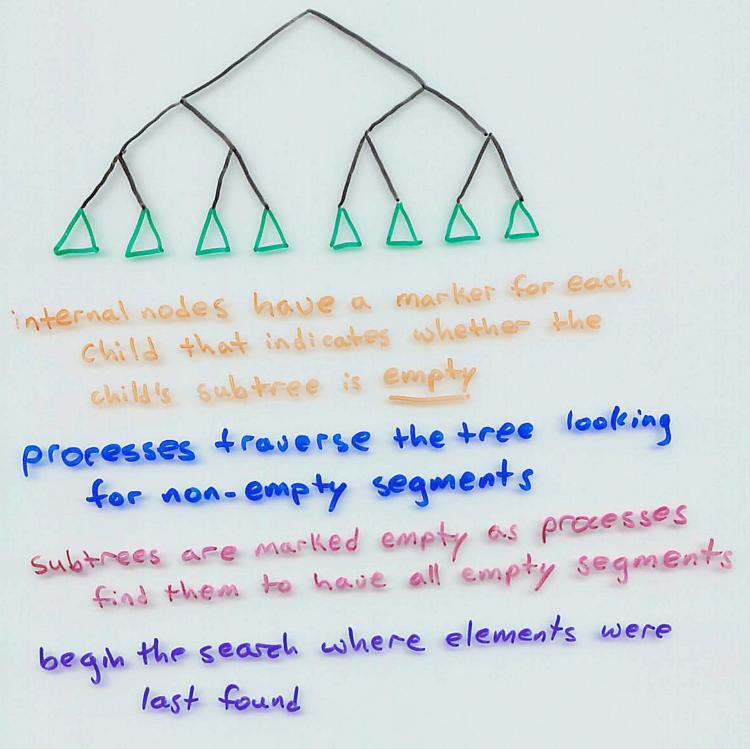
We compare 3 search algorithms

- . TREE
- . LINEAR
- . RANDOM



[Manber, SIAM J. Comput. 11/86]

Superimpose a tree on the segments:



LINEAR SEARCH

Try the segments in some fixed order



no information is hept about empty segments

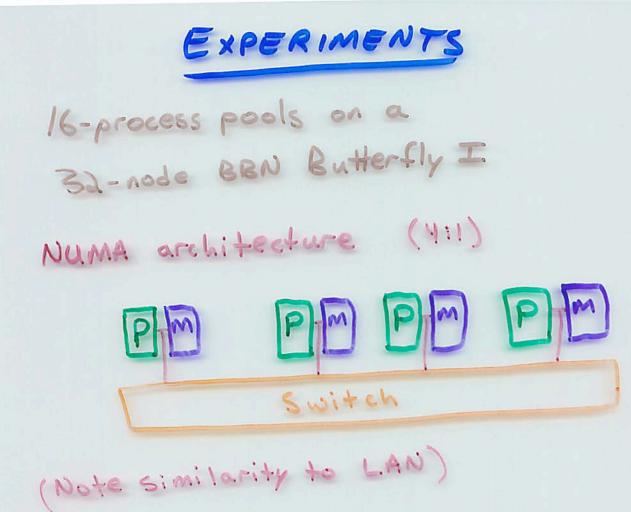
begin the search where elements were last found





Try the segments at random:





Implementations use local memory for add and remove, but must use remote memory for steals.



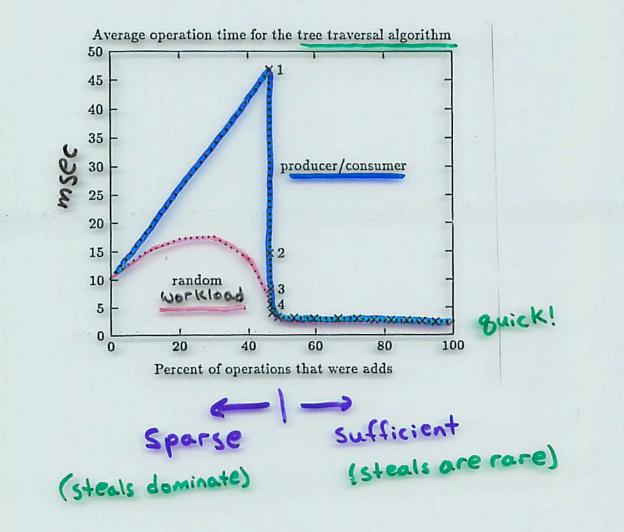
· STRESS FUL

· ENCOURAGE STEALS

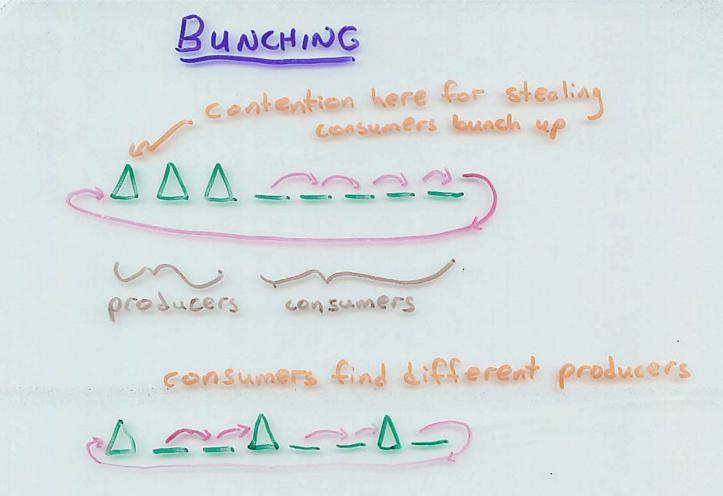
Two TYPES:

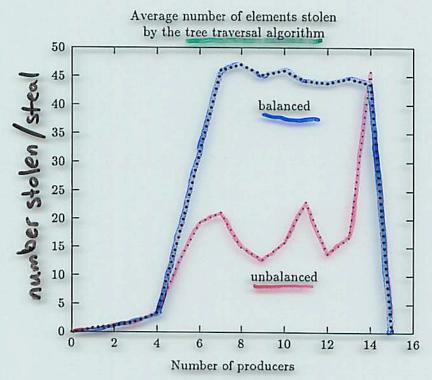
RANDOM
 All processes add and remove
 Uostying mix of add/remove
 Sparse: < 50% adds
 sufficient: > 50% adds
 sufficient: > 50% adds
 .PRODUCER (CONSUMER
 Some processes add
 Some processes add
 Some processes remove
 Vary number of producers
 Vary number of producers





As expected, steals determine performance





balancing the producers allows consumers to steal more on each steal, and to interfere less.

COMPARING ALGORITHMS · All 3 similar for producer/consumer · All 3 similar for random, sufficient loads · Tree search slow for random sparse loads This despite the fact that the tree search o examines fewer leaves o steals more elements -> lower overhead ? No, internal nodes of the tree add overhead as a source of contention. Traversing tree nodes similar in time to Examining a pool segment.



Tree search better for higher remote: local access time ratio?

e.g., distributed system

EXPERIMENT :

artificially delay access to "remote" parts of the pool (leaves, tree nodes) Delays from lasec ... 100 msec (Normal operation time ~ 100 msec)

RESULT:

· Free search never wins · All 3 become similar with high delay

Conclusion :

Complexity of tree search not worth it.



3-0 Tic-Tac-Toe game Minimox search tree of 3 levels and 250,000 nodes. Algorithm: Ald nodes to central work list. Remove node from list. Process node. Concrate new nodes to put on list.

Concurrent Pool: Peol for work list. Speedup of 14.6-15.4 on 16 procs. (Three search algorithms similar.) Global Stack: Used a simple, single stack for work list. Algorithm identical. 40% slower than pool speedup of only 10.7 on 16 procs.

SUMMARY

Concurrent peols provide an efficient, highly concurrent solution to many problems.

Locality of reference good - steal only when necessary - good for NUMA architectures.

Complex tree search not worth the effort needed to maintain the high locality, low interference.

Considerations of overhead need to be taken into account in design of concurrent data structures, including locality in NUMA architectures.

FUTURE WORK · other implementations of tree search algorithm? · Larger pools? (>16 processes) · Other search algorithms?

A talk by David Kotz, June 1989.

Presented at the Ninth International Conference on Distributed Computer Systems (ICDCS), in Newport Beach, California.

Describing the paper by David Kotz and Carla Ellis, "Evaluation of concurrent pools." In *Proceedings of the Ninth International Conference on Distributed Computer Systems (ICDCS),* pages 378-385. IEEE Computer Society Press, 1989.

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